Reduced-Cost Sensor & Node for Direct Measurements of CO₂ flux, Evapotranspiration, Sensible Heat Flux, PAR and Key Weather Parameters

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FLUX PROCESSING SCHEME

Raw Data	• U, V, W, Tsonic (vertical), Tsonic (Horizontal), CO ₂ , H ₂ O, Tair, Pressure, RH
Remove implausible values	Large spikes are removed
De-spiking	(Mauder et al, 2013) using Median Absolute Deviation
Time align U and V with W	Using cross covariance between vertical and horizontal Tsonic
Two-Dimensional Rotation	For tilt correction
Compute fast air temperature	Correct sonic temperature iteratively using mean air temperature
Compute fast air molar volume	\bullet Compute Fast H_2O mole fraction iteratively using RH probe and analyzer H_2O
Compute fast mixing ratios	• Using fast molar volume and CO $_2$ / H $_2$ O mole fractions
Compute covariances	 Covariance between W and H₂O / CO₂ mixing ratios are computed
Frequency response correction	Massman, 2000, 2001 methodology is implemented
Compute Fluxes	Buoyancy correction applied to heat flux
Compute turbulence parameters	Fraction velocity, stability parameters and others are computed
OA/OC Flags	Based on Mauder and Foken 2004 (0, 1, 2)

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Figure 3: Comparison of CO₂ flux, Latent heat and Sensible heat flux between the LI-720 and a traditional EC system at Mead, NE

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Variable	Preliminary specification	
CO ₂ Measurement	 Calibration Range: 0 to 1500 µmol mol⁻¹ 	
	Accuracy: Within 1.5% of reading	
	 Zero Drift (per °C): ±0.15 ppm typical, ±0.3 ppm maximum 	
	 RMS Noise (typical @ 400 µmol mol⁻¹ CO2): @10 Hz: 1.0 ppm 	
	 Direct Sensitivity to H2O (mol CO2 mol⁻¹ H2O): ±2.00E-05 typical, ±4.00E-05 maximum 	
H ₂ O Measurement	Calibration range: 0 to 60 mmol mol ⁻¹	
	Accuracy: Within 1.5% of reading	
	 Zero drift (per °C): ±0.03 mmol mol⁻¹ typical, ±0.05 mmol mol⁻¹ maximum 	
	 RMS noise (typical @ 10 mmol mol⁻¹ H₂O): @10 Hz: 0.05 mmol mol⁻¹ 	
	 Direct sensitivity to CO₂ (mol H₂O/mol CO₂): ±0.02 typical, ±0.05 maximum 	
Wind Measurement	 Measurement Axes: U, V, W 	
	 Measurement Range: 0 – 30 m s-1 (Horizontal Wind Conditions) 	
	 Offset at Zero Wind: ±0.06 m s-1 	
	 RMS Noise: <0.1 m s-1 @ 5 m s-1, <0.15 m s-1 @ 15 m s-1 	
	 Sonic Temperature Accuracy: ± 0.2°C Maximum offset at 20°C 	
Biomet	 Photosynthetic Photon Flux Density: Range: 0-3000 µmol m -2 s -1, 	
Measurements	Accuracy: ±5% of reading	
	 Cosine Correction: Corrected up to 75° angle of incidence. 	
	Biomet Air Temperature Range: -40 - 60°C Accuracy: ±1.5°C – No load conditions	
	Atmospheric Pressure Range: 50 – 110 kPa Accuracy: ±0.5 kPa typical	
	Biomet RH Range: 0-100 % - non-condensing Accuracy: ±1 % typical	

LI-7500DS



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*Indicates prototype units manufactured during the PDR (Preliminary Design Review) and *CDR (Critical Design Review) process *More information on the Carbon-Node is presented in the poster B11L-1476 **DESCRIPTION OF THE SENSOR**

INTRODUCTION



Figure 1: Image of the sensor showing the different components.

UNIQUE FEATURES OF THE LI-720

· Co-located wind and CO2/H2O measurements with intentionally minimized flow disturbance

Very low power consumption (~1.5 W)

from PDR* and CDR* units in the field.

- Measures biometeorological variables such as air temperature, atmospheric pressure, relative humidity and PAR
- · Compute fluxes with the collected data using standard processing algorithms with embedded custom code
- Provides raw data output via RS232 and flux output via SDI-12
- Features GPS for location and time keeping
- · Tilt and orientation outputs (magnetometer/accelerometer)
- No moving parts or temperature control
- Vertical and Horizontal components of wind are measure separately in a unique geometry to minimize distortion and allow the best vertical wind measurement
- · Features a broad band infrared analyzer with a modulated light source

B11L-1486



Figure 6: LI-720 sensor deployed on a Carbon-Node

CONCLUSIONS

The LI-720 is a low power, low-cost sensor primarily meant for carbon and water flux measurements

The sensor is designed for ease of use with only a single output cable and provides both high frequency raw data and processed fluxes.

Supporting biometeorological data such as PAR, air temperature, relative humidity and atmospheric pressure required for gap filling and flux processing are also provided. Preliminary field data indicates a performance very similar to a traditional Eddy Covariance systems

The LI-720 sensor coupled with a Carbon-Node™ provides an end-to-end solution for quantifying carbon budgets with automated outlier detection and gap filling.

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